

FIG. 2

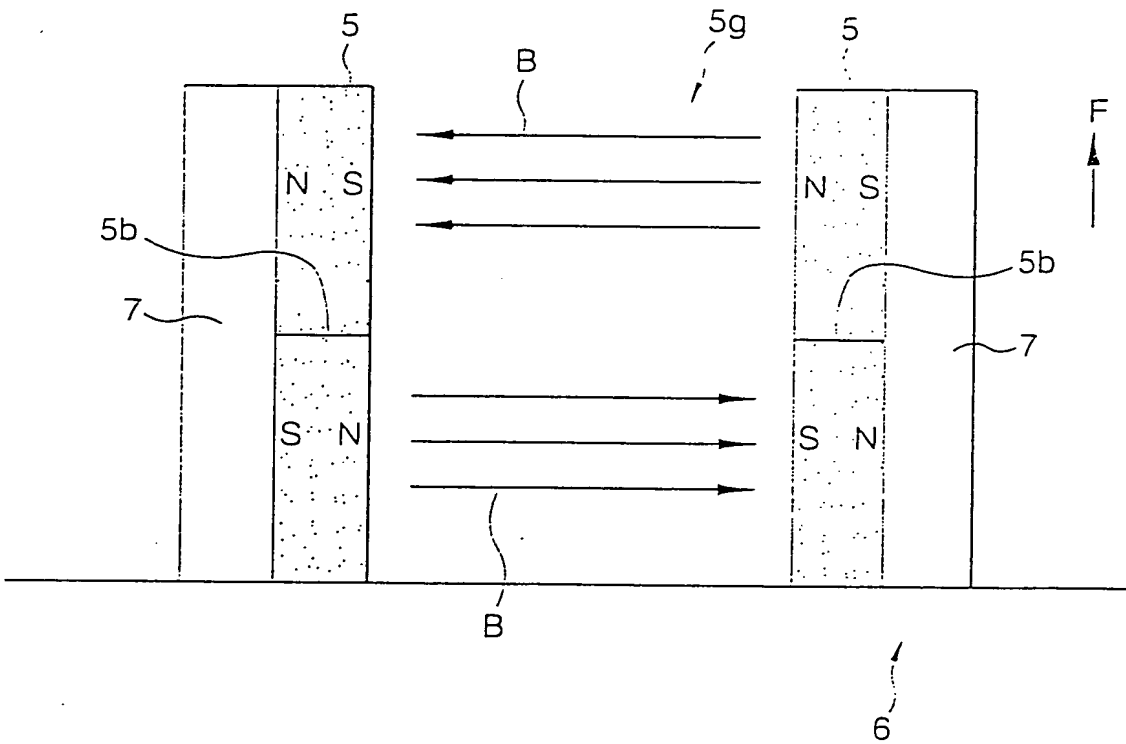


FIG. 3

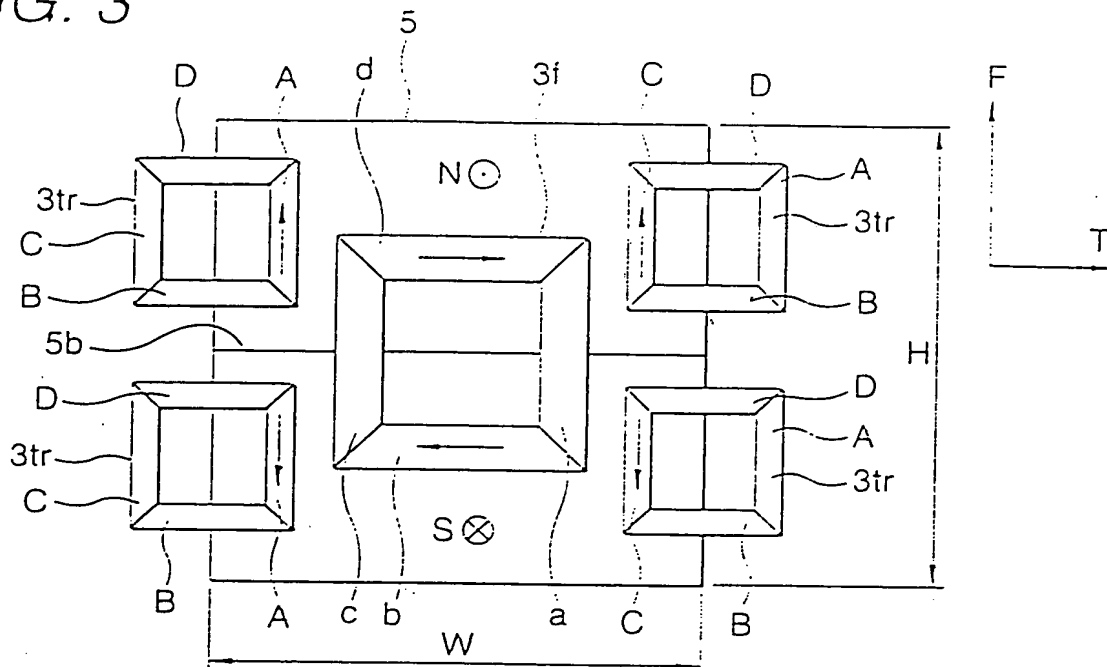


FIG. 4

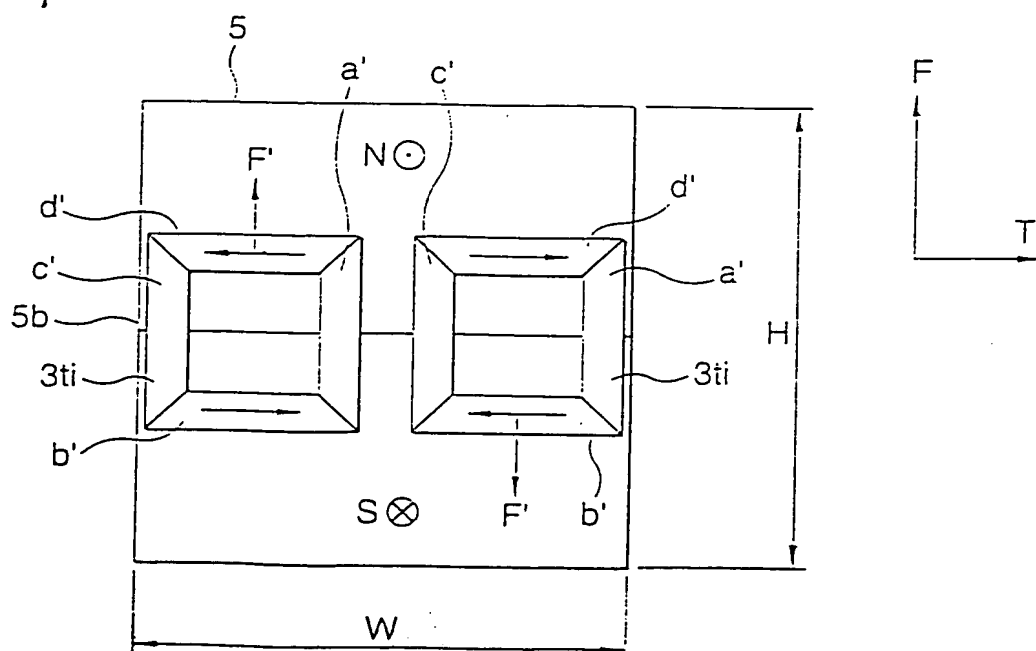


FIG. 5

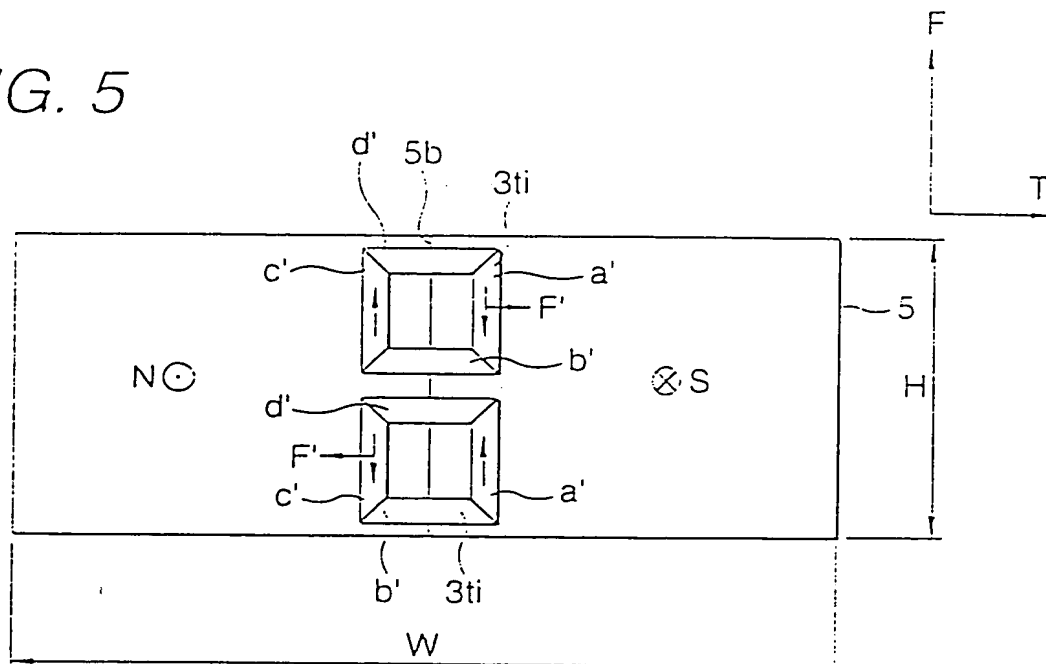


FIG. 6

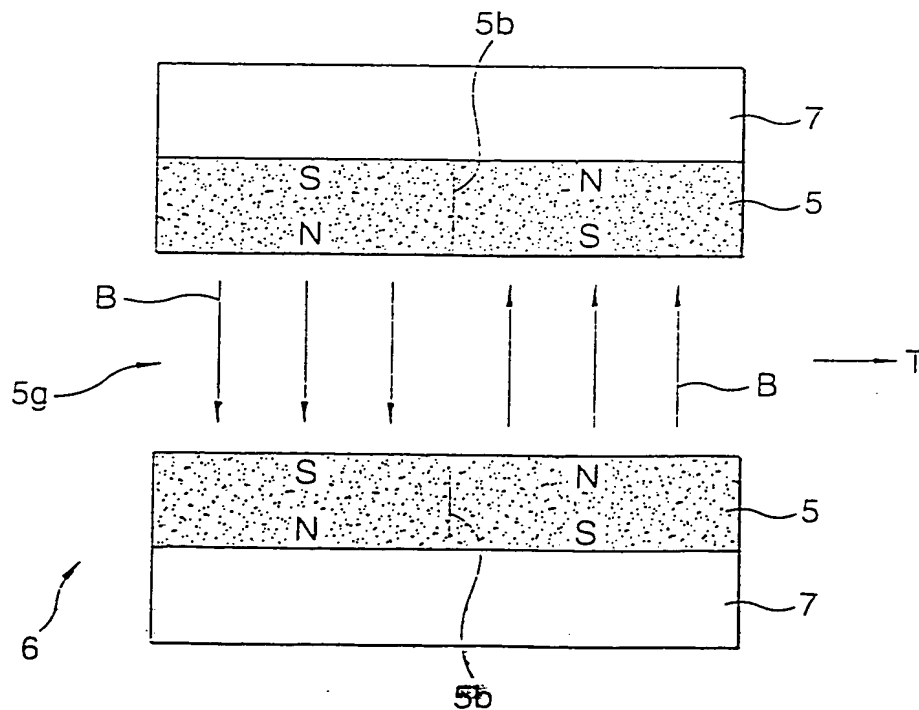


FIG. 7

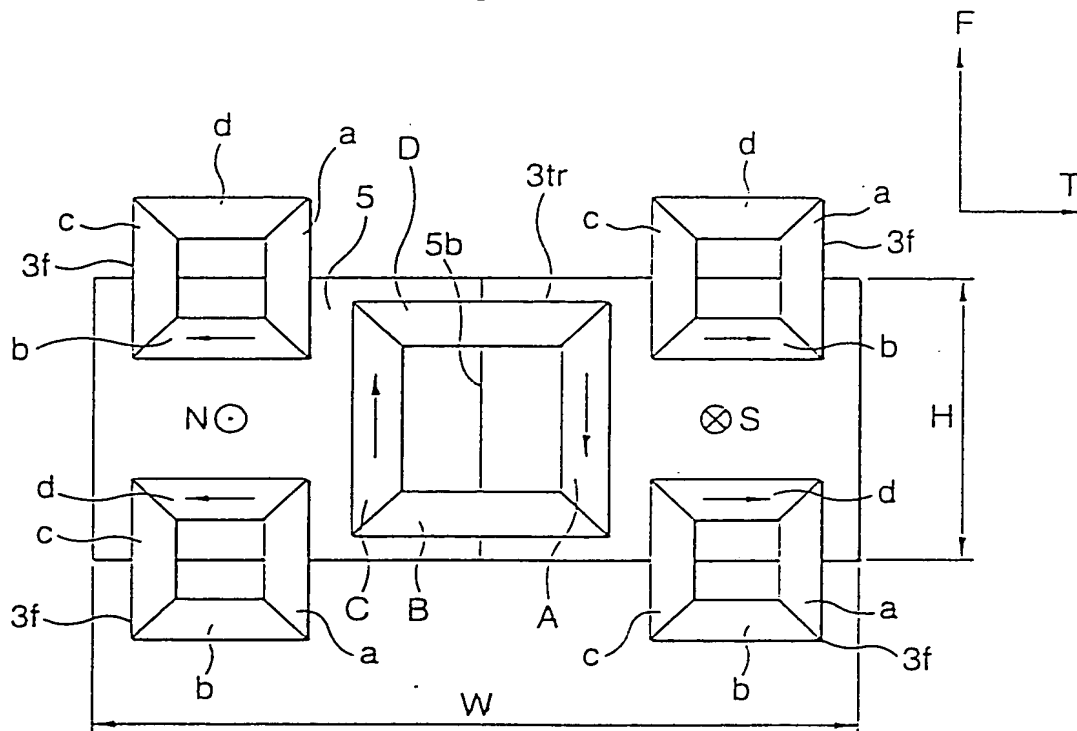


FIG. 8

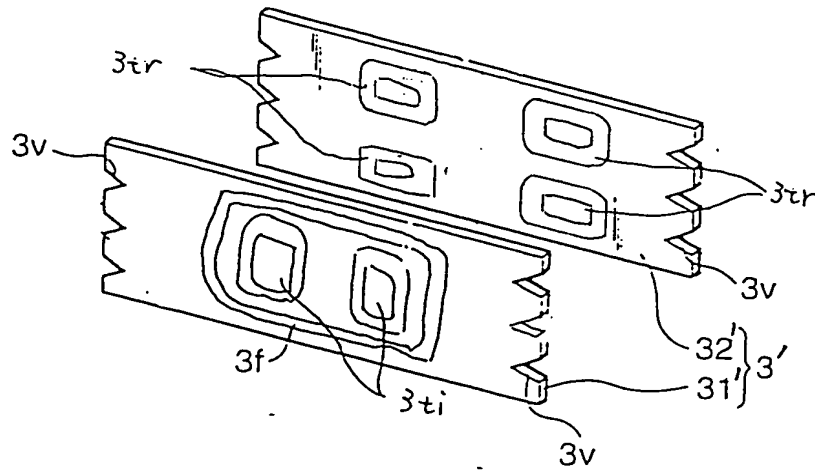


FIG. 8

FIG. 10

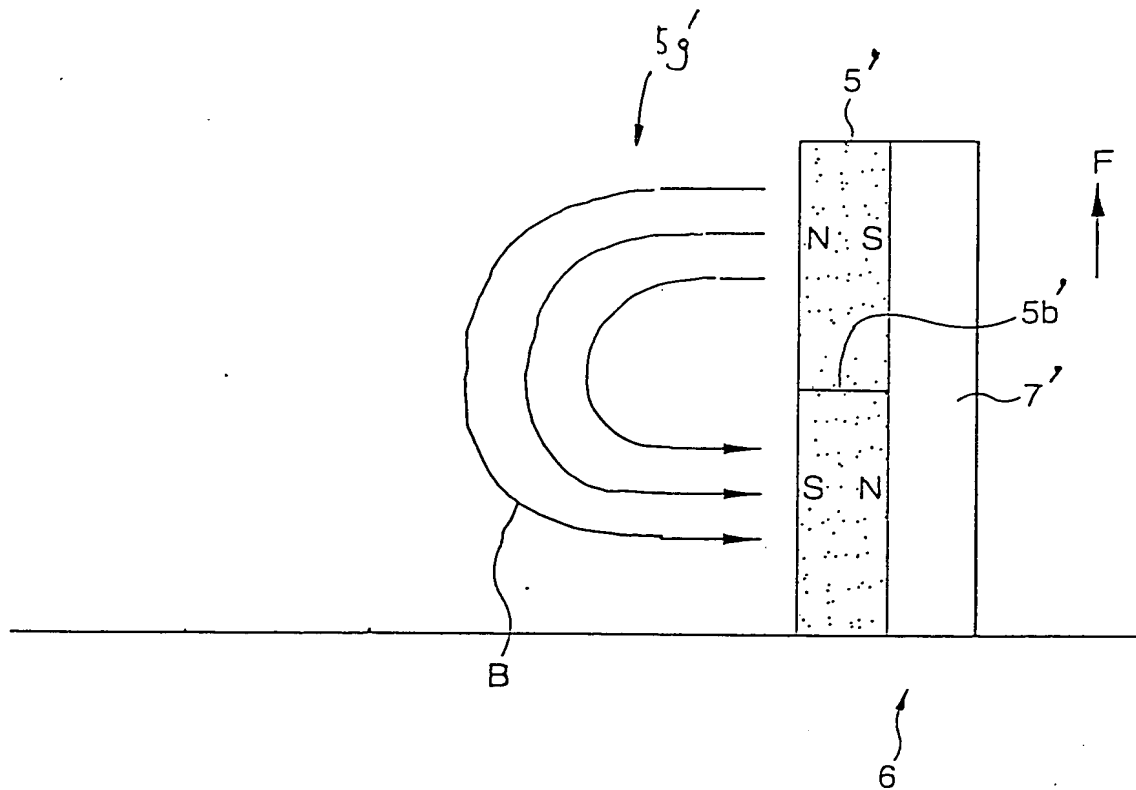


FIG. 13A

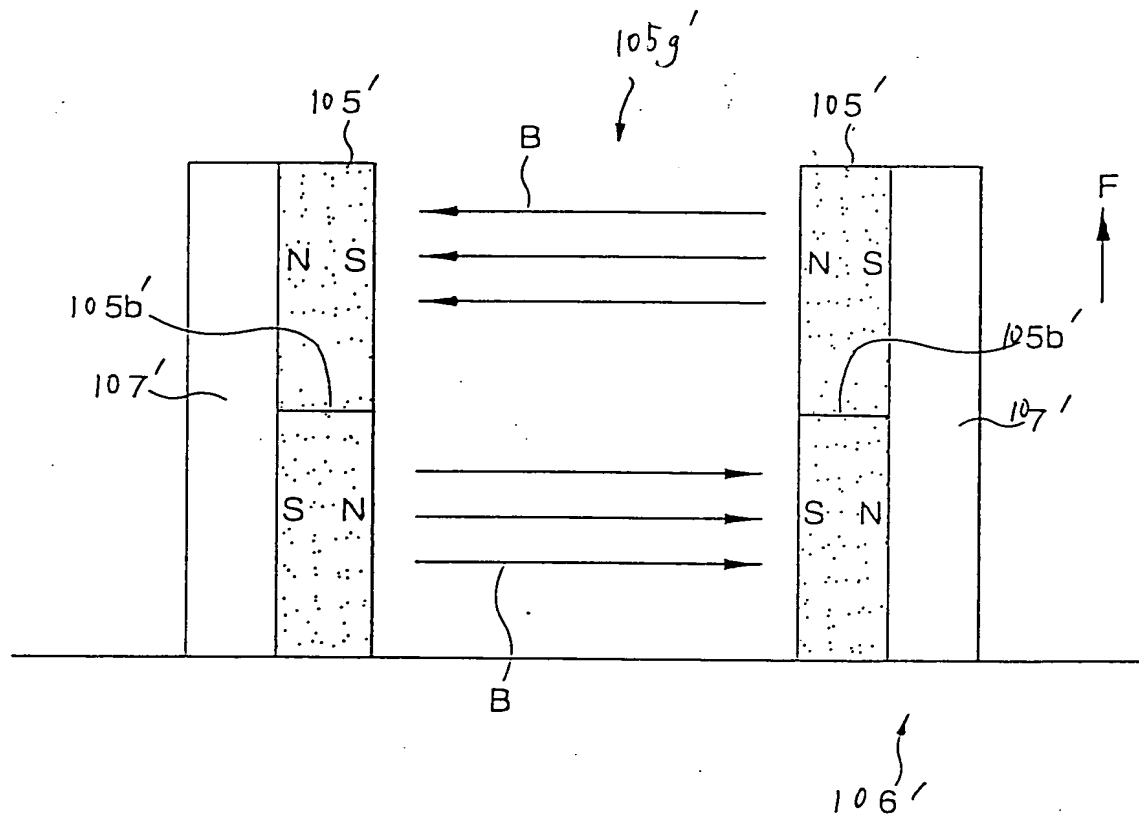


FIG. 13B

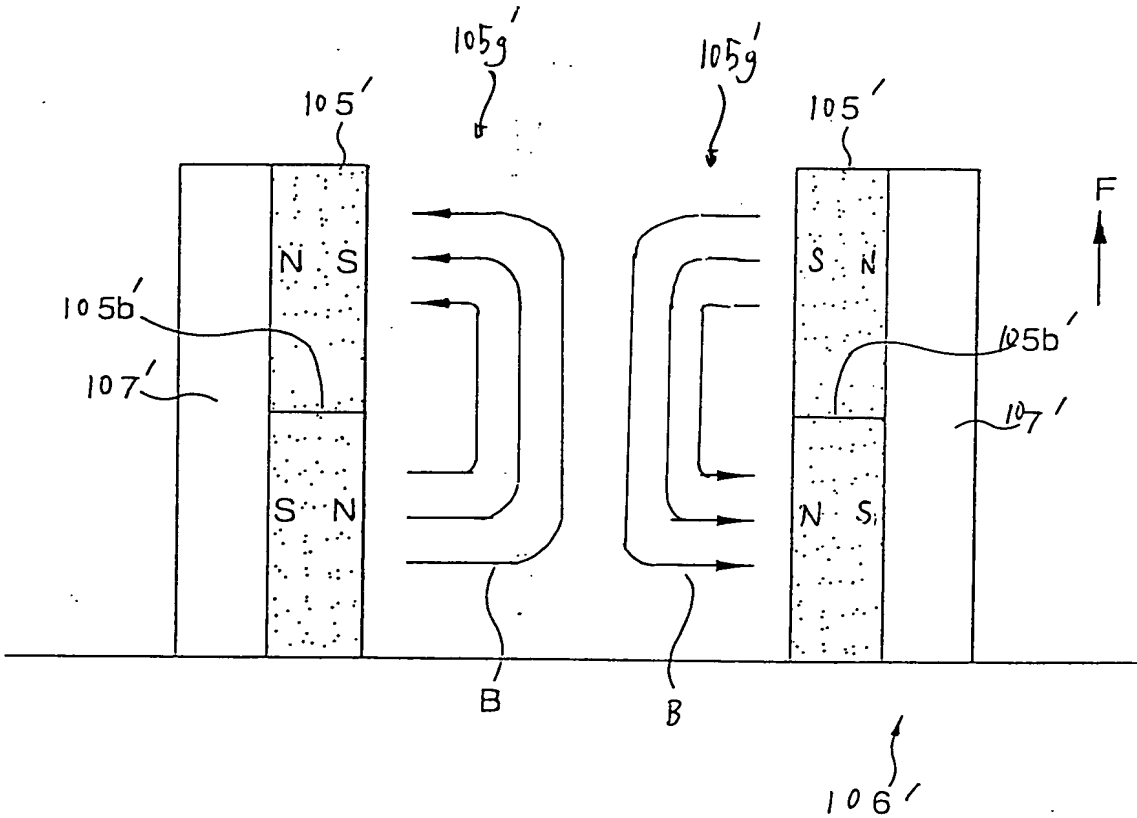


FIG. 14

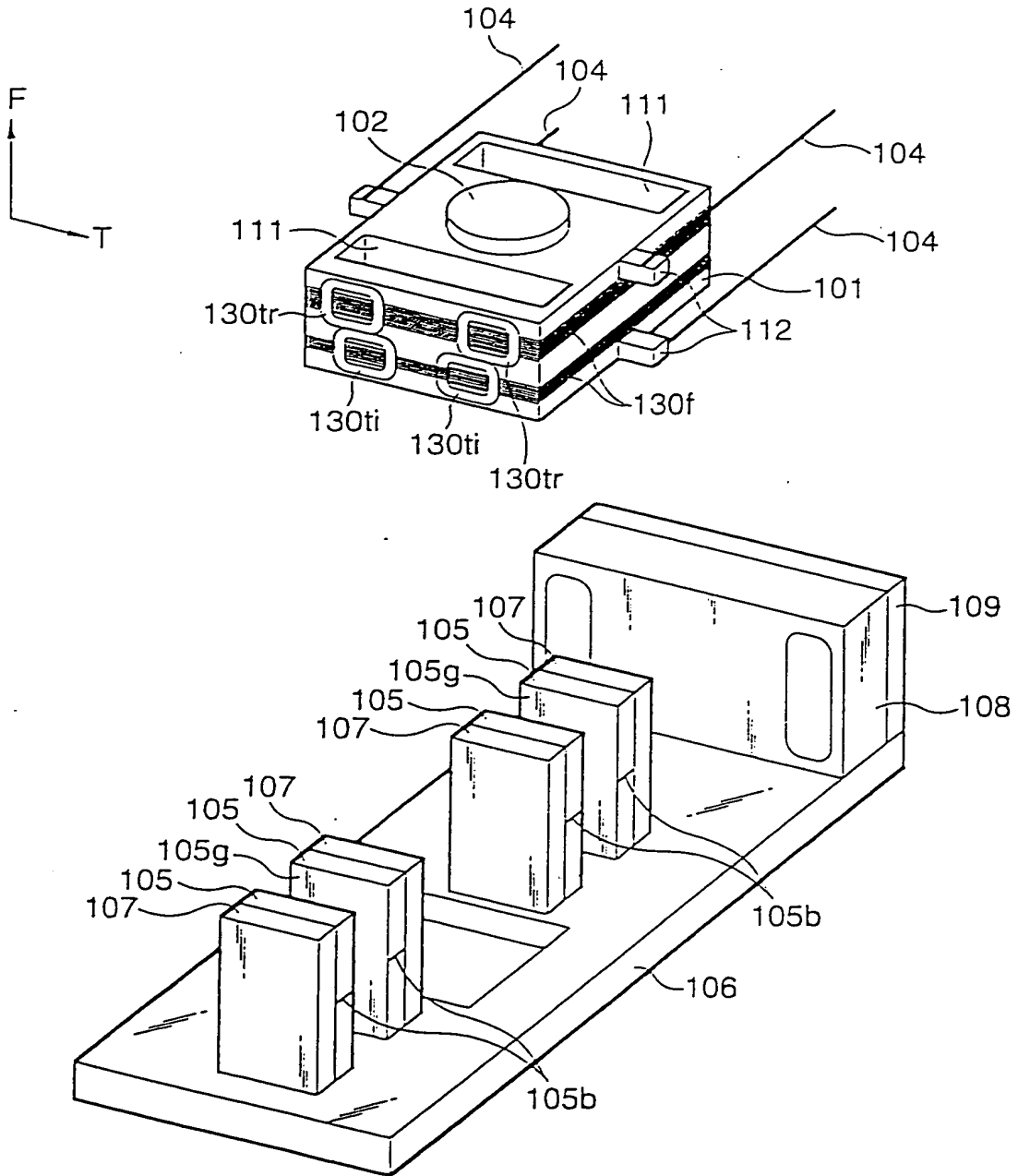


FIG. 15

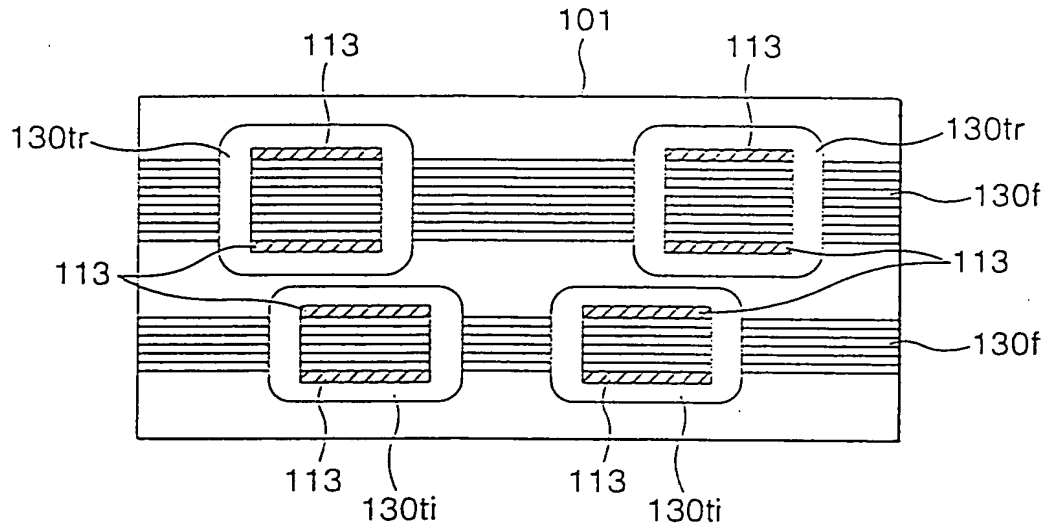


FIG. 16

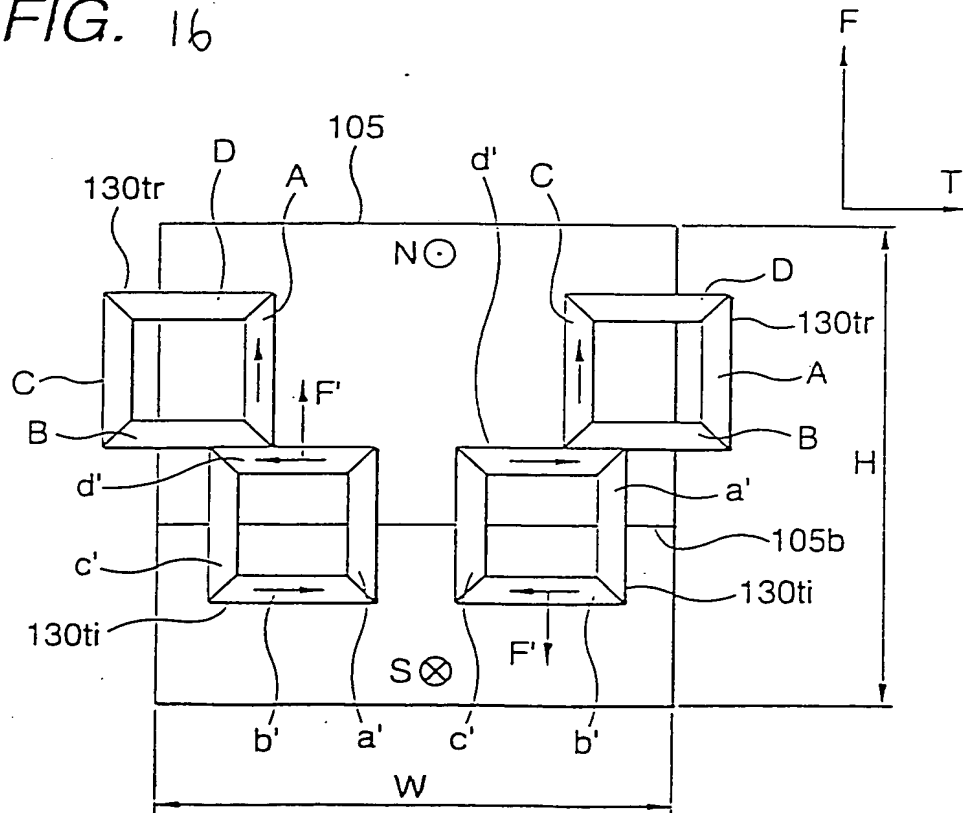


FIG. 17

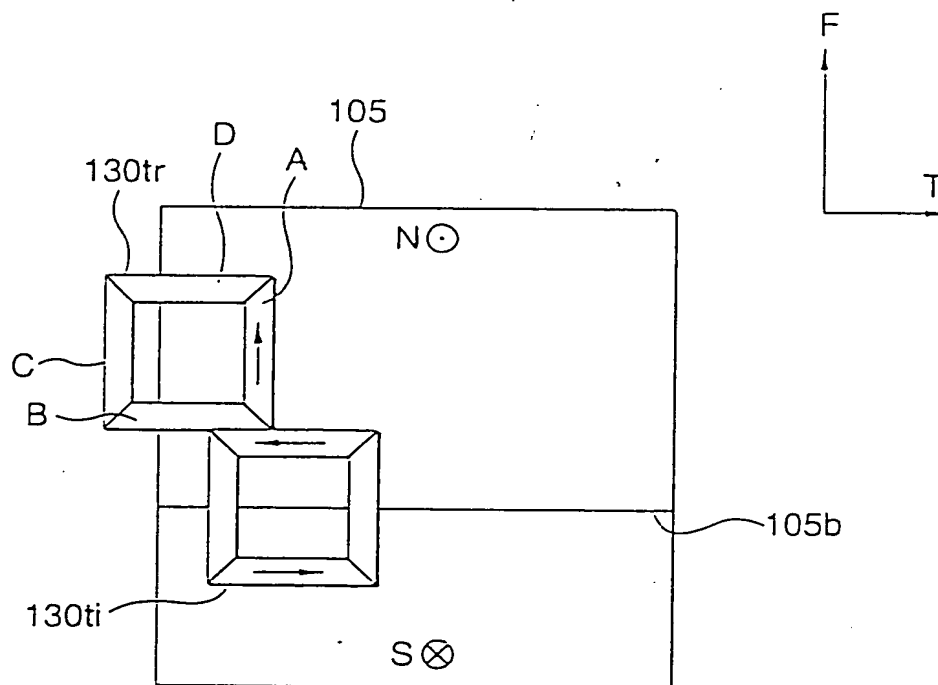


FIG. 19

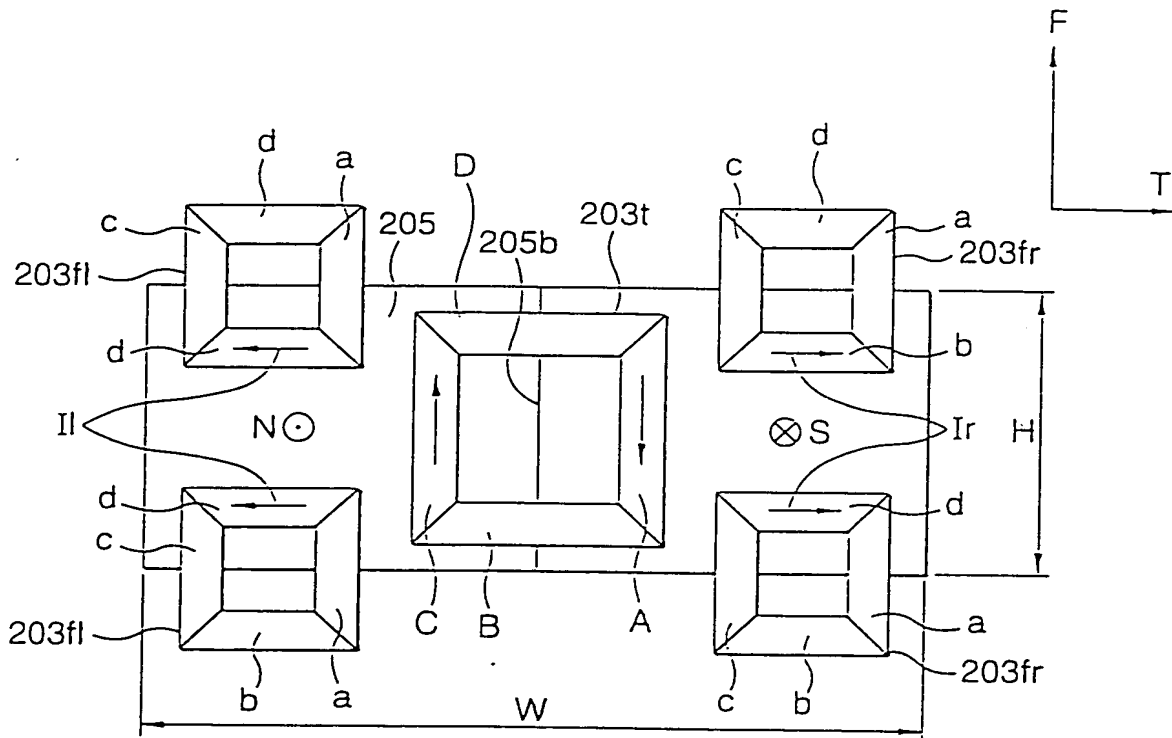


FIG. 20

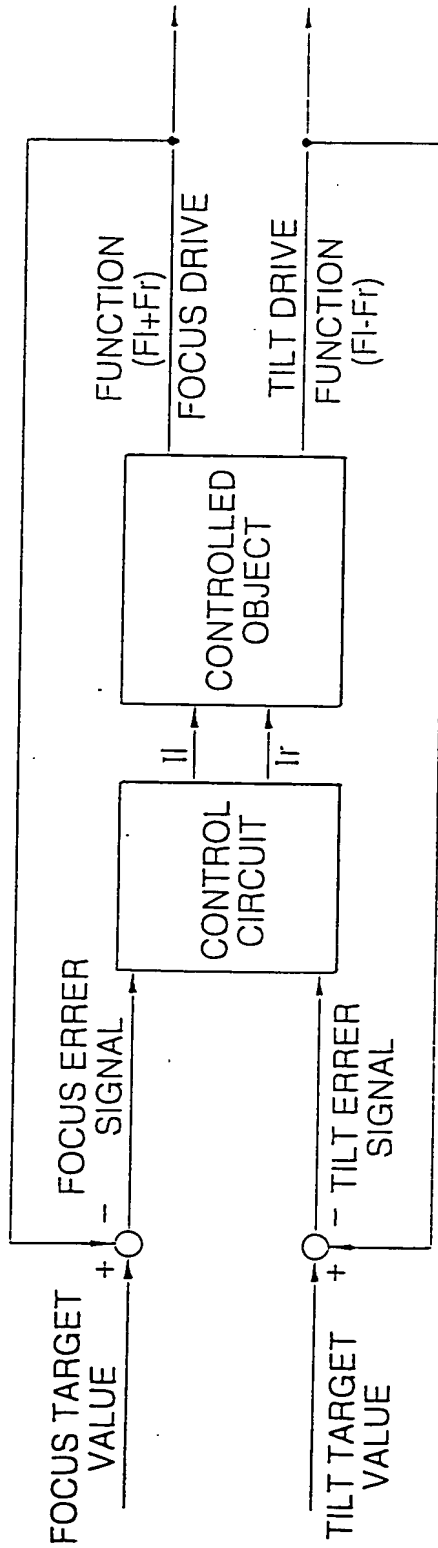


FIG. 21.A

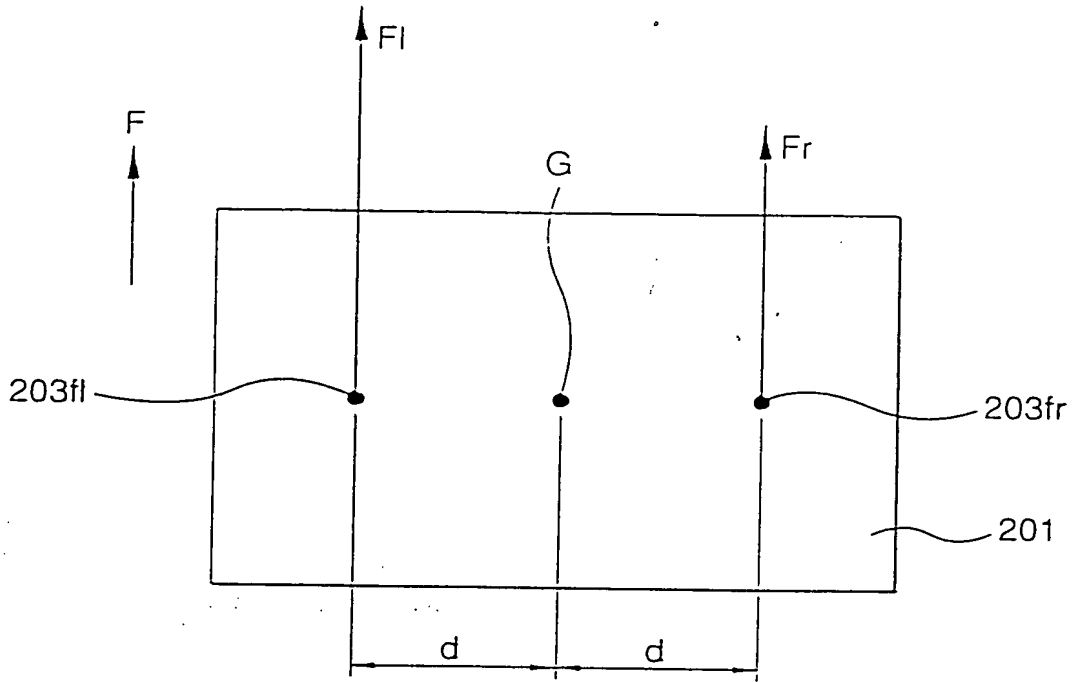


FIG. 21.B

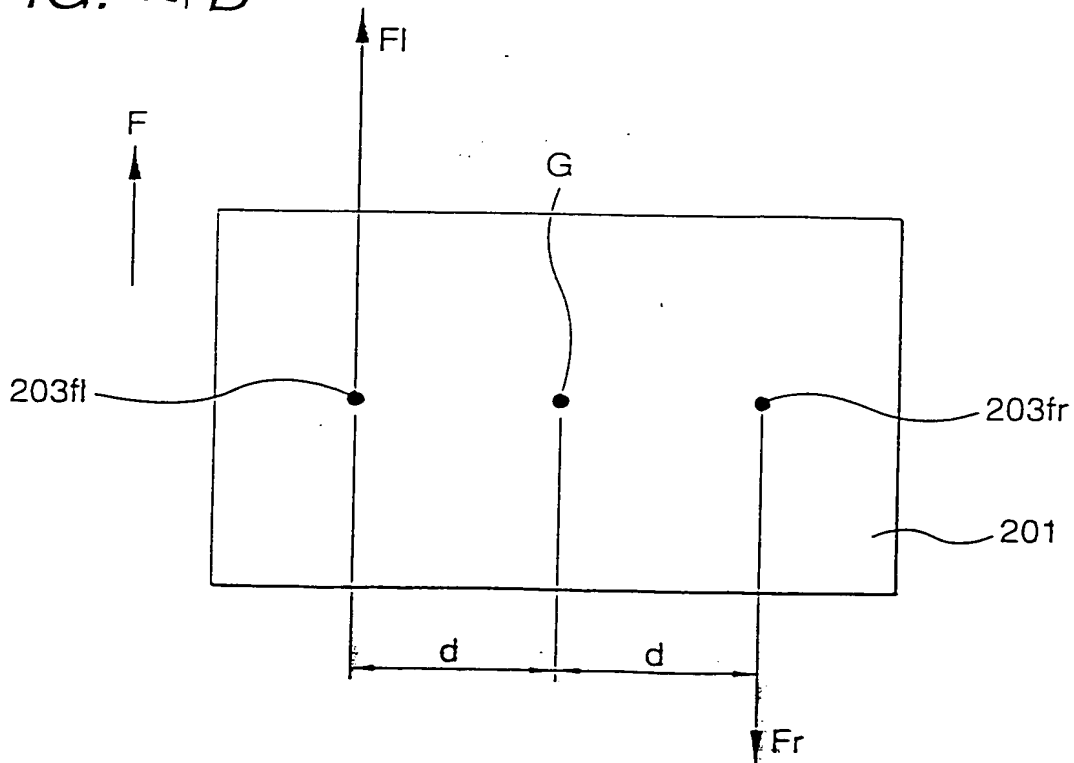


Figure 1 is a schematic diagram of a magnetic field measurement system. The system includes a sample 201 with a circular feature 202, mounted on a base 206. A magnetic field source 203 is positioned above the sample, with a magnetic field vector F and a torque vector T indicated. The source 203 has a top surface 203tu, a bottom surface 203f, and a side surface 203p. It is connected to a power supply 204 via leads 203h and 203v. The base 206 has a rectangular opening 205 and a side wall 207. A magnetic field vector F is shown pointing upwards, and a torque vector T is shown pointing to the right.

FIG. 24

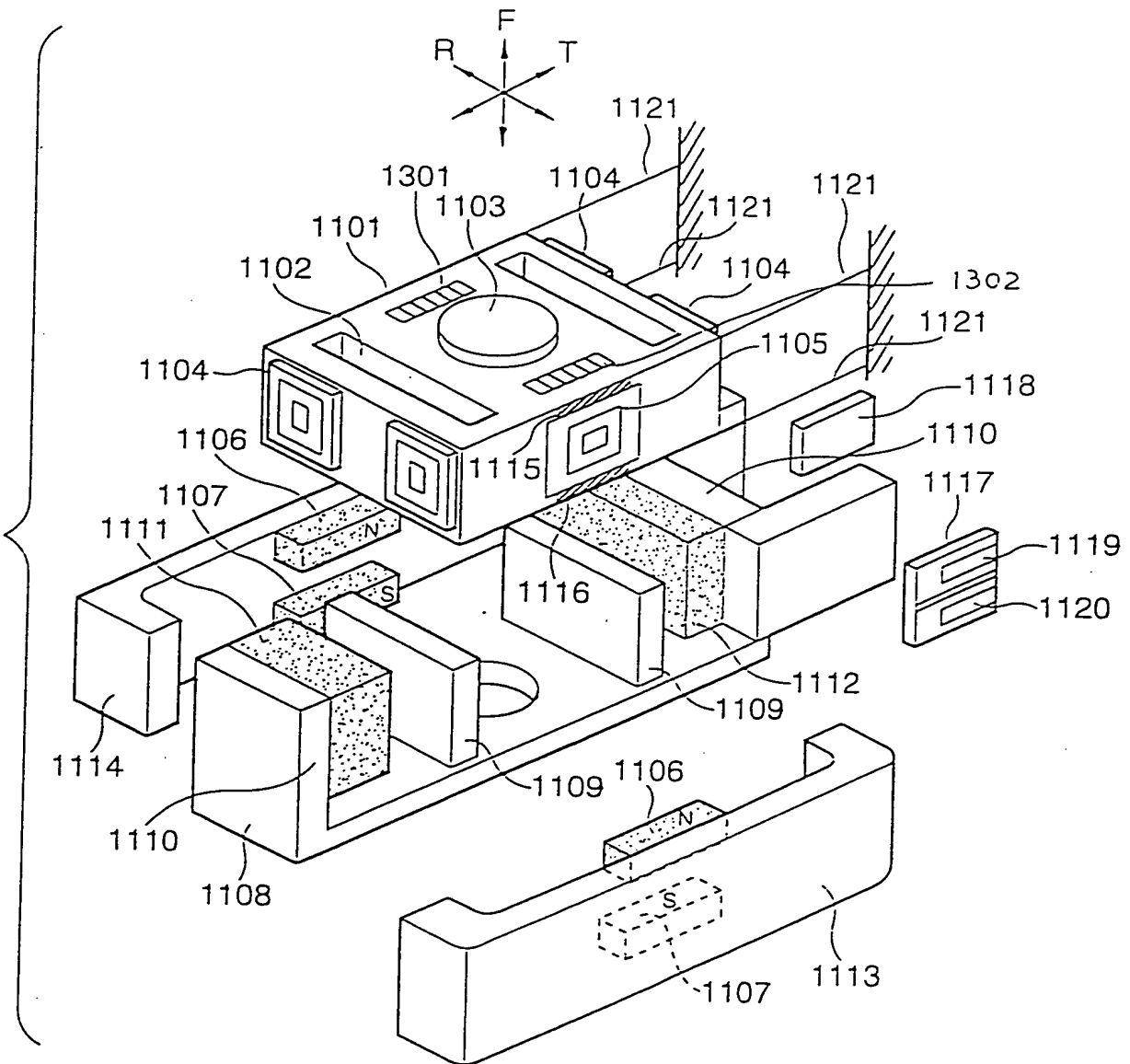


FIG. 24

[illegible]

FIG. 27

